

**16384 x 1 BIT DYNAMIC MOS  
RANDOM ACCESS MEMORY**

**DESCRIPTION** The NEC μPD416 is a 16384 words by 1 bit Dynamic MOS RAM. It is designed for memory applications where very low cost and large bit storage are important design objectives.

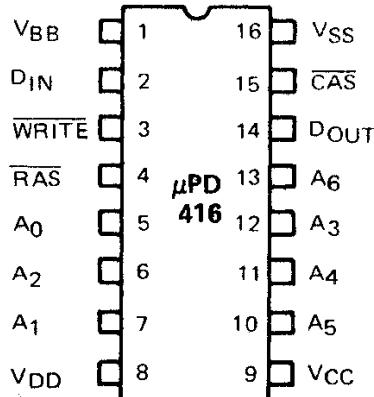
The μPD416 is fabricated using a double-poly-layer N channel silicon gate process which affords high storage cell density and high performance. The use of dynamic circuitry throughout, including the sense amplifiers, assures minimal power dissipation.

Multiplexed address inputs permit the μPD416 to be packaged in the standard 16 pin dual-in-line package. The 16 pin package provides the highest system bit densities and is available in either ceramic or plastic. Noncritical clock timing requirements allow use of the multiplexing technique while maintaining high performance.

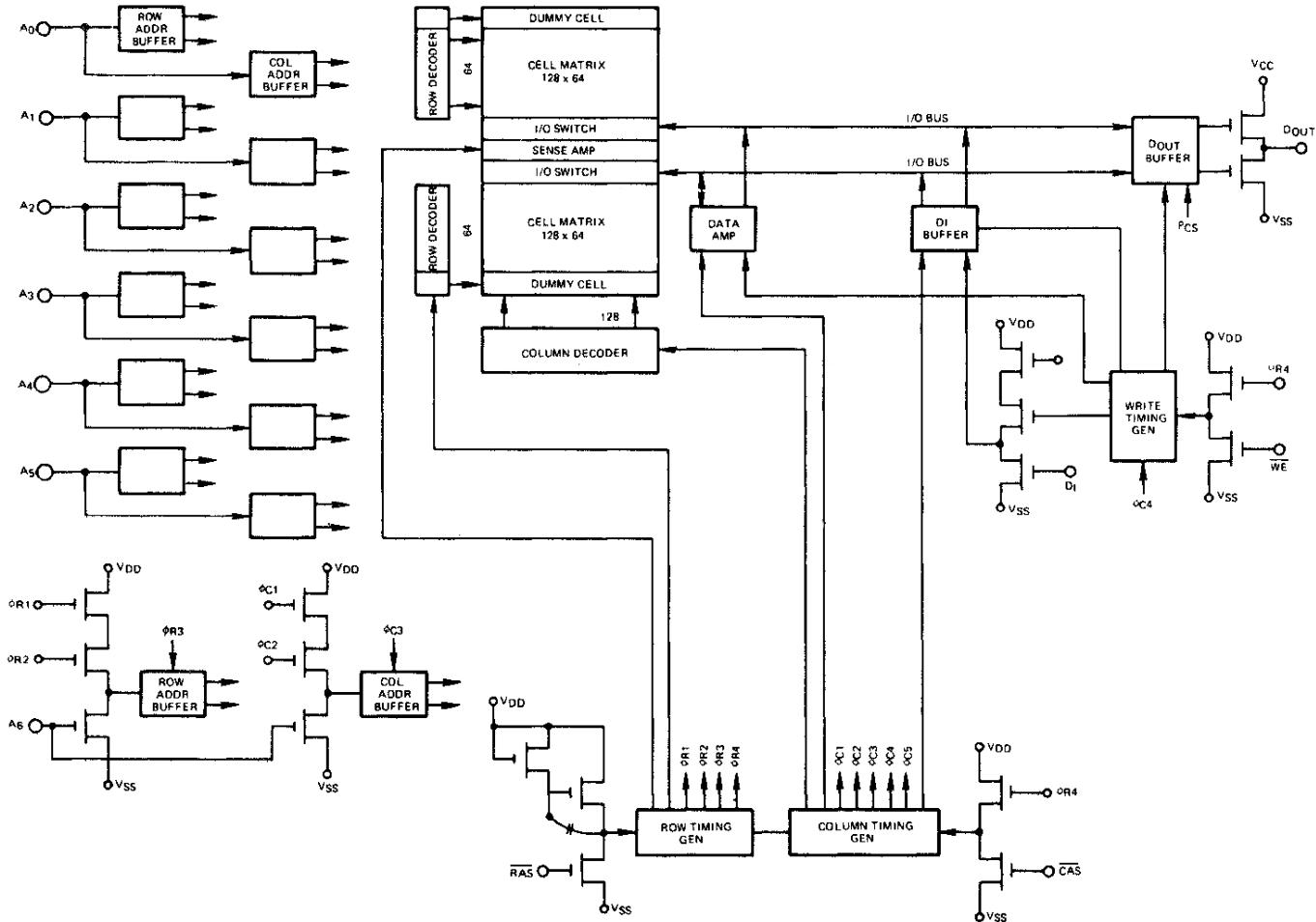
**FEATURES**

- 16384 Words x 1 Bit Organization
- High Memory Density – 16 Pin Ceramic and Plastic Packages
- Multiplexed Address Inputs
- Standard Power Supplies +12V, -5V, +5V
- Low Power Dissipation; 462 mW Active (MAX), 40 mW Standby (MAX)
- Output Data Controlled by CAS and Unlatched at End of Cycle
- Read-Modify-Write, RAS-only Refresh, and Page Mode Capability
- All Inputs TTL Compatible, and Low Capacitance
- 128 Refresh Cycles
- 5 Performance Ranges:

|          | ACCESS TIME | R/W CYCLE | RMW CYCLE |
|----------|-------------|-----------|-----------|
| μPD416   | 300 ns      | 510 ns    | 575 ns    |
| μPD416-1 | 250 ns      | 410 ns    | 465 ns    |
| μPD416-2 | 200 ns      | 375 ns    | 375 ns    |
| μPD416-3 | 150 ns      | 375 ns    | 375 ns    |
| μPD416-5 | 120 ns      | 320 ns    | 320 ns    |

**PIN CONFIGURATION**

|                  |                       |
|------------------|-----------------------|
| A0-A6            | Address Inputs        |
| CAS              | Column Address Strobe |
| D <sub>IN</sub>  | Data In               |
| D <sub>OUT</sub> | Data Out              |
| RAS              | Row Address Strobe    |
| WR <sub>TE</sub> | Read/Write            |
| V <sub>BB</sub>  | Power (-5V)           |
| V <sub>CC</sub>  | Power (+5V)           |
| V <sub>DD</sub>  | Power (+12V)          |
| V <sub>SS</sub>  | Ground                |



|   |   |
|---|---|
| Operating Temperature . . . . .   | $0^{\circ}\text{C}$ to $+70^{\circ}\text{C}$    |
| Storage Temperature . . . . .   | $-55^{\circ}\text{C}$ to $+150^{\circ}\text{C}$ |
| All Output Voltages ① . . . . .   | -0.5 to +20 Volts                               |
| All Input Voltages ① . . . . .  | -0.5 to +20 Volts                               |
| Supply Voltages V <sub>DD</sub> , V <sub>CC</sub> , V <sub>SS</sub> ① . . . . . | -0.5 to +20 Volts                               |
| Supply Voltages V <sub>DD</sub> , V <sub>CC</sub> ② . . . . .                   | -1.0 to +15 Volts                               |
| Short Circuit Output Current . . . . .  | 50 mA   |
| Power Dissipation . . . . .   | 1 Watt  |

Notes: ① Relative to V<sub>BB</sub>  
       ② Relative to V<sub>SS</sub>

COMMENT: Stress above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

\*T<sub>a</sub> = 25°C

T<sub>a</sub> = 0°C to 70°C, V<sub>DD</sub> = +12V ± 10%, V<sub>BB</sub> = -5V ± 10%, V<sub>CC</sub> = +5V ± 10%,  
     V<sub>SS</sub> = 0V

| PARAMETER  | SYMBOL          | LIMITS |     |     | UNIT | TEST CONDITIONS |
|--|-----------------|--------|-----|-----|------|-----------------|
|  |                 | MIN    | TYP | MAX |      |                 |
| Input Capacitance (A <sub>0</sub> -A <sub>6</sub> ), D <sub>IN</sub> | C <sub>I1</sub> |        | 4   | 5   | pF   |                 |
| Input Capacitance RAS, CAS, WRITE                                    | C <sub>I2</sub> |        | 8   | 10  | pF   |                 |
| Output Capacitance (D <sub>OUT</sub> )                               | C <sub>O</sub>  |        | 5   | 7   | pF   |                 |

$T_a = 0^\circ C$  to  $+70^\circ C$  (1),  $V_{DD} = +12V \pm 10\%$ ,  $V_{CC} = +5V \pm 10\%$ ,  $V_{BB} = -5V \pm 10\%$ ,  $V_{SS} = 0V$

| PARAMETER  | SYMBOL                          | LIMITS    |      |      | UNIT    | TEST CONDITIONS   |
|--|---------------------------------|-----------|------|------|---------|---|
|  |                                 | MIN       | Typ  | MAX  |         |   |
| Supply Voltage   | $V_{DD}$                        | 10.8      | 12.0 | 13.2 | V       | (2)   |
| Supply Voltage   | $V_{CC}$                        | 4.5       | 5.0  | 5.5  | V       | (2) (3)   |
| Supply Voltage   | $V_{SS}$                        | 0         | 0    | 0    | V       | (2)   |
| Supply Voltage   | $V_{BB}$                        | -4.5      | -5.0 | -5.5 | V       | (2)   |
| Input High (Logic 1) Voltage, RAS, CAS, WRITE                  | $V_{IHC}$                       | 2.7       |      | 7.0  | V       | (2)   |
| Input High (Logic 1) Voltage, all inputs except RAS, CAS WRITE | $V_{IH}$                        | 2.4       |      | 7.0  | V       | (2)   |
| Input Low (Logic 0) Voltage, all inputs                        | $V_{IL}$                        | 1.0       |      | 0.8  | V       | (2)   |
| Operating $V_{DD}$ Current                                     | $I_{DD1}$                       |           |      | 35   | mA      | RAS, CAS cycling; $t_{RC} = t_{RC}$ Min. (4)                                      |
| Standby $V_{DD}$ Current                                       | $I_{DD2}$                       |           |      | 1.5  | mA      | $RAS = V_{IHC}$ , DOUT = High Impedance   |
| Refresh $V_{DD}$ Current                                       | All Speeds except $\mu PD416-5$ | $I_{DD3}$ |      | 25   | mA      | $RAS$ cycling, $CAS = V_{IHC}$ ; $t_{RC} = 375$ ns (4)                            |
|  | $\mu PD416-5$                   | $I_{DD3}$ |      | 27   | mA      | $RAS = V_{IHC}$ , CAS cycling; $t_{PC} = 225$ ns (4)                              |
| Page Mode $V_{DD}$ Current                                     | $I_{DD4}$                       |           |      | 27   | mA      | $RAS = V_{IL}$ , CAS cycling; $t_{PC} = 225$ ns (4)                               |
| Operating $V_{CC}$ Current                                     | $I_{CC1}$                       |           |      |      | $\mu A$ | $RAS$ , CAS cycling, $t_{RC} = 375$ ns (5)  |
| Standby $V_{CC}$ Current                                       | $I_{CC2}$                       | -10       |      | 10   | $\mu A$ | $RAS = V_{IHC}$ , DOUT = High Impedance   |
| Refresh $V_{CC}$ Current                                       | $I_{CC3}$                       | -10       |      | 10   | $\mu A$ | $RAS$ cycling, $CAS = V_{IHC}$ , $t_{RC} = 375$ ns                                |
| Page Mode $V_{CC}$ Current                                     | $I_{CC4}$                       |           |      |      | $\mu A$ | $RAS = V_{IL}$ , CAS cycling, $t_{PC} = 225$ ns (5)                               |
| Operating $V_{BB}$ Current                                     | $I_{BB1}$                       |           |      | 200  | $\mu A$ | $RAS$ , CAS cycling, $t_{RC} = 375$ ns  |
| Standby $V_{BB}$ Current                                       | $I_{BB2}$                       |           |      | 100  | $\mu A$ | $RAS = V_{IHC}$ , DOUT = High Impedance   |
| Refresh $V_{BB}$ Current                                       | $I_{BB3}$                       |           |      | 200  | $\mu A$ | $RAS$ cycling, $CAS = V_{IHC}$ , $t_{RC} = 375$ ns                                |
| Page Mode $V_{BB}$ Current                                     | $I_{BB4}$                       |           |      | 200  | $\mu A$ | $RAS = V_{IL}$ , CAS cycling; $t_{PC} = 225$ ns                                   |
| Input Leakage (any input)                                      | $I_{I(L)}$                      | -10       |      | 10   | $\mu A$ | $V_{BB} = -5V$ , $0V \leq V_{IN} \leq +7V$ , all other pins not under test = $0V$ |
| Output Leakage   | $I_{O(L)}$                      | -10       |      | 10   | $\mu A$ | DOUT is disabled, $0V \leq V_{OUT} \leq +5.5V$                                    |
| Output High Voltage (Logic 1)                                  | $V_{OH}$                        | 2.4       |      |      | V       | $I_{OUT} = -5$ mA (3)   |
| Output Low Voltage (Logic 0)                                   | $V_{OL}$                        |           |      | 0.4  | V       | $I_{OUT} = 4.2$ mA  |

Notes: (1)  $T_a$  is specified here for operation at frequencies to  $t_{RC} \geq t_{RC}$  (min). Operation at higher cycle rates with reduced ambient temperatures and high power dissipation is permissible, however, provided AC operating parameters are met. See Figure 1 for derating curve.

(2) All voltages referenced to  $V_{SS}$ .

(3) Output voltage will swing from  $V_{SS}$  to  $V_{CC}$  when activated with no current loading. For purposes of maintaining data in standby mode,  $V_{CC}$  may be reduced to  $V_{SS}$  without affecting refresh operations or data retention. However, the  $V_{OH}$  (min) specification is not guaranteed in this mode.

(4)  $I_{DD1}$ ,  $I_{DD3}$ , and  $I_{DD4}$  depend on cycle rate. See Figures 2, 3 and 4 for  $I_{DD}$  limits at other cycle rates.

(5)  $I_{CC1}$  and  $I_{CC4}$  depend upon output loading. During readout of high level data  $V_{CC}$  is connected through a low impedance ( $135\Omega$  typ) to data out. At all other times  $I_{CC}$  consists of leakage currents only.

$T_a = 0^\circ\text{C}$  to  $+70^\circ\text{C}$ ,  $V_{DD} = +12\text{V} \pm 10\%$ ,  $V_{CC} = +5\text{V} \pm 10\%$ ,  $V_{BB} = -5\text{V} \pm 10\%$ ,  $V_{SS} = 0\text{V}$

| PARAMETER                                     | SYMBOL    | LIMITS            |        |                     |        |                     |        |                     |        |                     |        | UNIT | TEST CONDITIONS |  |  |
|---|-----------|-------------------|--------|---------------------|--------|---------------------|--------|---------------------|--------|---------------------|--------|------|-----------------|--|--|
|   |           | $\mu\text{PD416}$ |        | $\mu\text{PD416-1}$ |        | $\mu\text{PD416-2}$ |        | $\mu\text{PD416-3}$ |        | $\mu\text{PD416-5}$ |        |      |                 |  |  |
|   |           | MIN               | MAX    | MIN                 | MAX    | MIN                 | MAX    | MIN                 | MAX    | MIN                 | MAX    |      |                 |  |  |
| Random read or write cycle time               | $t_{RC}$  | 610               |        | 410                 |        | 375                 |        | 320                 |        | 320                 |        | ns   | ③               |  |  |
| Read-write cycle time                         | $t_{RWC}$ | 575               |        | 465                 |        | 375                 |        | 375                 |        | 320                 |        | ns   | ③               |  |  |
| Page mode cycle time                          | $t_{PC}$  | 330               |        | 275                 |        | 225                 |        | 170                 |        | 160                 |        | ns   |                 |  |  |
| Access time from RAS                          | $t_{RAC}$ |                   | 300    |                     | 250    |                     | 200    |                     | 150    |                     | 120    | ns   | ④ ⑥             |  |  |
| Access time from CAS                          | $t_{CAC}$ |                   | 200    |                     | 165    |                     | 135    |                     | 100    |                     | 80     | ns   | ⑤ ⑥             |  |  |
| Output buffer turn-off delay                  | $t_{OFF}$ | 0                 | 80     | 0                   | 60     | 0                   | 50     | 0                   | 40     | 0                   | 35     | ns   | ⑦               |  |  |
| Transition time (rise and fall)               | $t_T$     | 3                 | 50     | 3                   | 50     | 3                   | 50     | 3                   | 35     | 3                   | 35     | ns   | ②               |  |  |
| RAS precharge time                            | $t_{RP}$  | 200               |        | 150                 |        | 120                 |        | 100                 |        | 100                 |        | ns   |                 |  |  |
| RAS pulse width                               | $t_{RAS}$ | 300               | 10,000 | 250                 | 10,000 | 200                 | 32,000 | 150                 | 32,000 | 120                 | 10,000 | ns   |                 |  |  |
| RAS hold time                                 | $t_{RSH}$ | 200               |        | 165                 |        | 135                 |        | 100                 |        | 80                  |        | ns   |                 |  |  |
| CAS pulse width                               | $t_{CAS}$ | 200               | 10,000 | 165                 | 10,000 | 135                 | 10,000 | 100                 | 10,000 | 80                  | 10,000 | ns   |                 |  |  |
| RAS to CAS delay time                         | $t_{RCD}$ | 40                | 100    | 35                  | 85     | 25                  | 65     | 20                  | 50     | 15                  | 40     | ns   | ⑧               |  |  |
| CAS to RAS precharge time                     | $t_{CRP}$ | -20               |        | -20                 |        | -20                 |        | -20                 |        | 0                   |        | ns   |                 |  |  |
| Row address set-up time                       | $t_{ASR}$ | 0                 |        | 0                   |        | 0                   |        | 0                   |        | 0                   |        | ns   |                 |  |  |
| Row address hold time                         | $t_{RAH}$ | 40                |        | 35                  |        | 25                  |        | 20                  |        | 15                  |        | ns   |                 |  |  |
| Column address set-up time                    | $t_{ASC}$ | -10               |        | -10                 |        | -10                 |        | -10                 |        | -10                 |        | ns   |                 |  |  |
| Column address hold time                      | $t_{CAH}$ | 90                |        | 75                  |        | 55                  |        | 45                  |        | 40                  |        | ns   |                 |  |  |
| Column address hold time referenced to RAS    | $t_{AR}$  | 190               |        | 160                 |        | 120                 |        | 95                  |        | 80                  |        | ns   |                 |  |  |
| Read command set-up time                      | $t_{RCS}$ | 0                 |        | 0                   |        | 0                   |        | 0                   |        | 0                   |        | ns   |                 |  |  |
| Read command hold time                        | $t_{RCH}$ | 0                 |        | 0                   |        | 0                   |        | 0                   |        | 0                   |        | ns   |                 |  |  |
| Write command hold time                       | $t_{WCH}$ | 90                |        | 75                  |        | 55                  |        | 45                  |        | 40                  |        | ns   |                 |  |  |
| Write command hold time referenced to RAS     | $t_{WCR}$ | 190               |        | 160                 |        | 120                 |        | 95                  |        | 80                  |        | ns   |                 |  |  |
| Write command pulse width                     | $t_{WP}$  | 90                |        | 75                  |        | 55                  |        | 45                  |        | 40                  |        | ns   |                 |  |  |
| Write command to RAS lead time                | $t_{RWL}$ | 120               |        | 85                  |        | 70                  |        | 50                  |        | 50                  |        | ns   |                 |  |  |
| Write command to CAS lead time                | $t_{CWL}$ | 120               |        | 85                  |        | 70                  |        | 50                  |        | 50                  |        | ns   |                 |  |  |
| Data-in set-up time                           | $t_{DS}$  | 0                 |        | 0                   |        | 0                   |        | 0                   |        | 0                   |        | ns   | ⑨               |  |  |
| Data-in hold time                             | $t_{DH}$  | 90                |        | 75                  |        | 55                  |        | 45                  |        | 40                  |        | ns   | ⑨               |  |  |
| Data-in hold time referenced to RAS           | $t_{DHR}$ | 190               |        | 160                 |        | 120                 |        | 95                  |        | 80                  |        | ns   |                 |  |  |
| CAS precharge time (for page mode cycle only) | $t_{CP}$  | 120               |        | 100                 |        | 80                  |        | 60                  |        | 60                  |        | ns   |                 |  |  |
| Refresh period                                | $t_{REF}$ |                   | 2      |                     | 2      |                     | 2      |                     | 2      |                     | 2      | ms   |                 |  |  |
| WRITE command set-up time                     | $t_{WCS}$ | -20               |        | -20                 |        | -20                 |        | -20                 |        | 0                   |        | ns   | ⑩               |  |  |
| CAS to WRITE delay                            | $t_{CWD}$ | 140               |        | 125                 |        | 95                  |        | 70                  |        | 80                  |        | ns   | ⑩               |  |  |
| RAS to WRITE delay                            | $t_{RWD}$ | 240               |        | 200                 |        | 160                 |        | 120                 |        | 120                 |        | ns   | ⑩               |  |  |

Notes: ① AC measurements assume  $t_T = 5\text{ ns}$ .

②  $V_{IH(\text{min})}$  or  $V_{IH(\text{min})}$  and  $V_{IL(\text{max})}$  are reference levels for measuring timing of input signals. Also, transition times are measured between  $V_{IH(\text{min})}$  or  $V_{IH(\text{min})}$  and  $V_{IL(\text{max})}$ .

③ The specifications for  $t_{RC}$  (min) and  $t_{RWC}$  (min) are used only to indicate cycle time at which proper operation over the full temperature range ( $0^\circ\text{C} \leq T_a \leq 70^\circ\text{C}$ ) is assured.

④ Assumes that  $t_{RCD} \leq t_{RCD}$  (max). If  $t_{RCD}$  is greater than the maximum recommended value shown in this table,  $t_{RAC}$  will increase by the amount that  $t_{RCD}$  exceeds the values shown.

⑤ Assumes that  $t_{RCD} \geq t_{RCD}$  (max).

⑥ Measured with a load equivalent to 2 TTL loads and 100 pF.

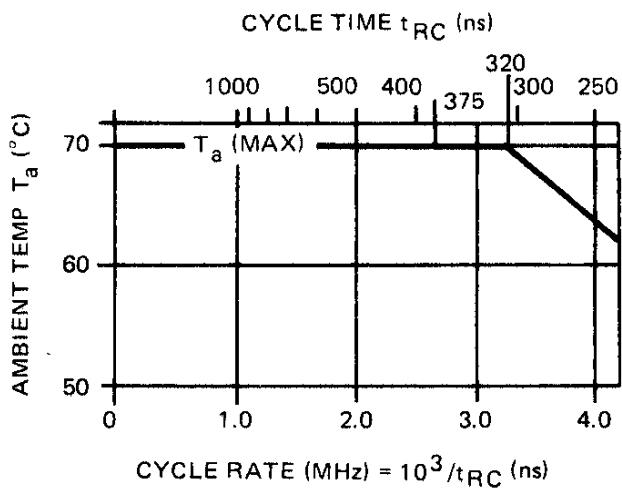
⑦  $t_{OFF}$  (max) defines the time at which the output achieves the open circuit condition and is not referenced to output voltage levels.

⑧ Operation within the  $t_{RCD}$  (max) limit ensures that  $t_{RAC}$  (max) can be met;  $t_{RCD}$  (max) is specified as a reference point only; if  $t_{RCD}$  is greater than the specified  $t_{RCD}$  (max) limit, then access time is controlled exclusively by  $t_{CAC}$ .

⑨ These parameters are referenced to CAS leading edge in early write cycles and to WRITE leading edge in delayed write or read-modify-write cycles.

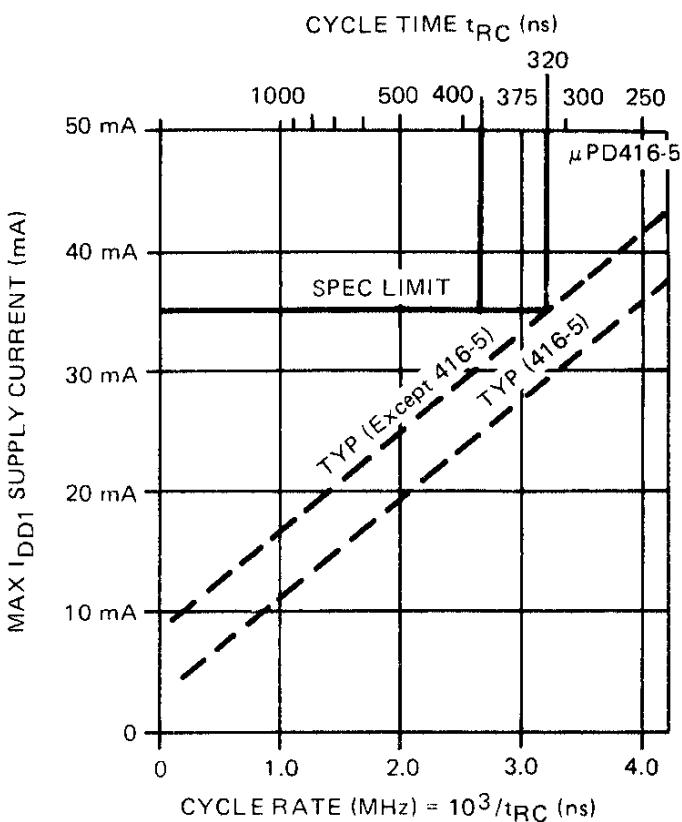
⑩  $t_{WCS}$ ,  $t_{CWD}$  and  $t_{RWD}$  are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If  $t_{WCS} \geq t_{WCS}$  (min), the cycle is an early write cycle and the data out pin will remain open circuit (high impedance)  $\geq t_{RWD}$  (min), the cycle is a read-write cycle and the data out will contain data read from the selected cell; if neither of the above sets of conditions is satisfied the condition of the data out (at access time) is indeterminate.

## DERATING CURVES



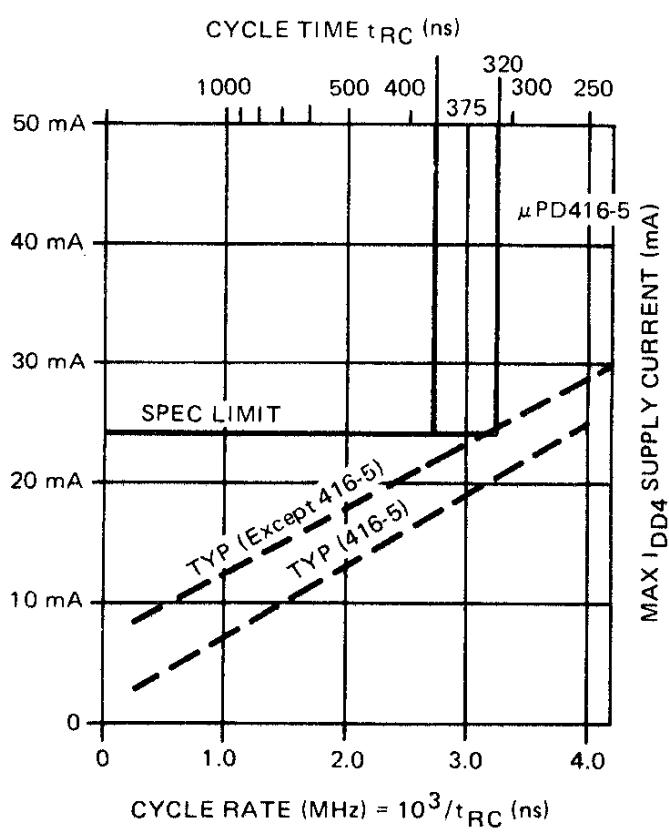
**FIGURE 1**

Maximum ambient temperature versus cycle rate for extended frequency operation.  $T_a$  (max) for operation at cycling rates greater than 2.66 MHz ( $t_{RC} < 375$  ns) is determined by  $T_a$  (max) [°C] = 70 - 9.0 x (cycle rate [MHz] - 2.66). For  $\mu$ PD416-5, it is  $T_a$  (max) [°C] = 70 - 9.0 (cycle rate [MHz] - 3.125).



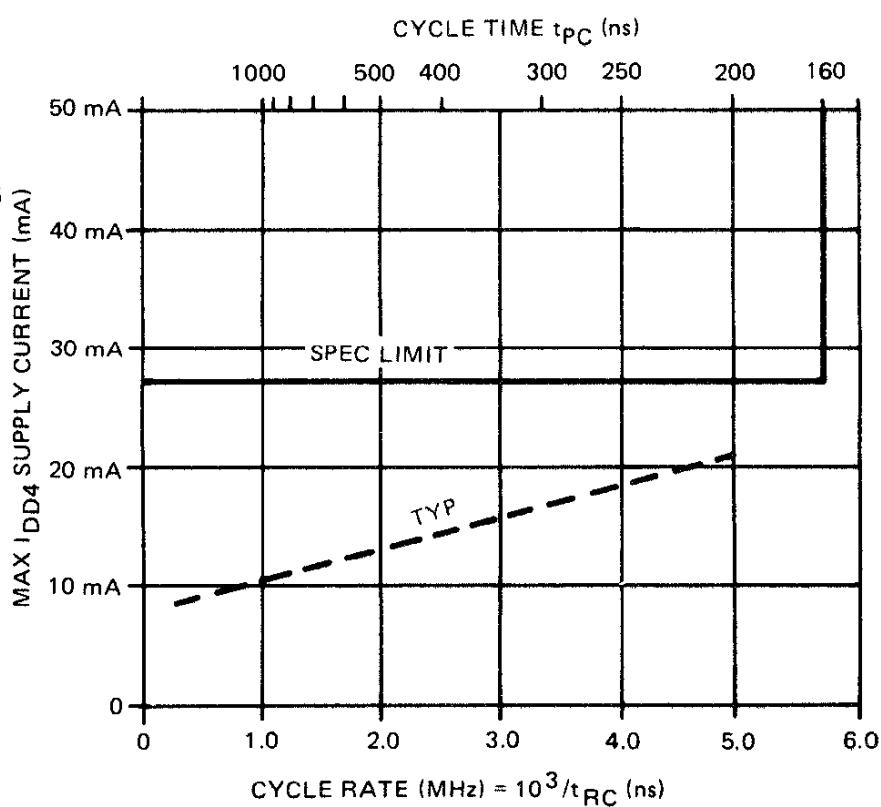
**FIGURE 2**

Maximum  $I_{DD1}$  versus cycle rate for device operation at extended frequencies.



**FIGURE 3**

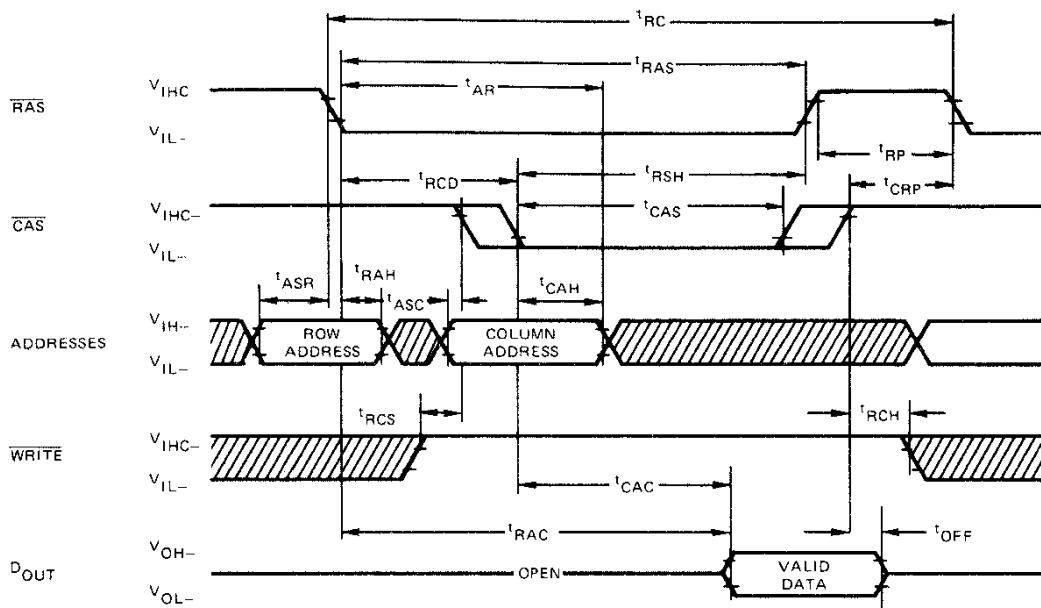
Maximum  $I_{DD3}$  versus cycle rate for device operation at extended frequencies.



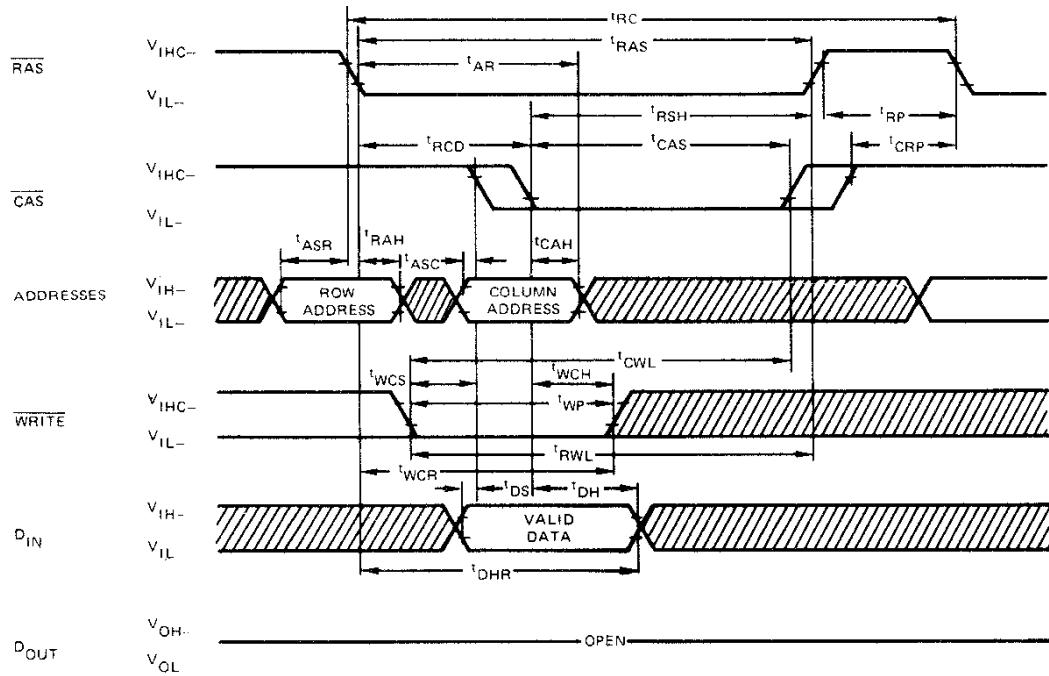
**FIGURE 4**

Maximum  $I_{DD4}$  versus cycle rate for device operation in page mode.

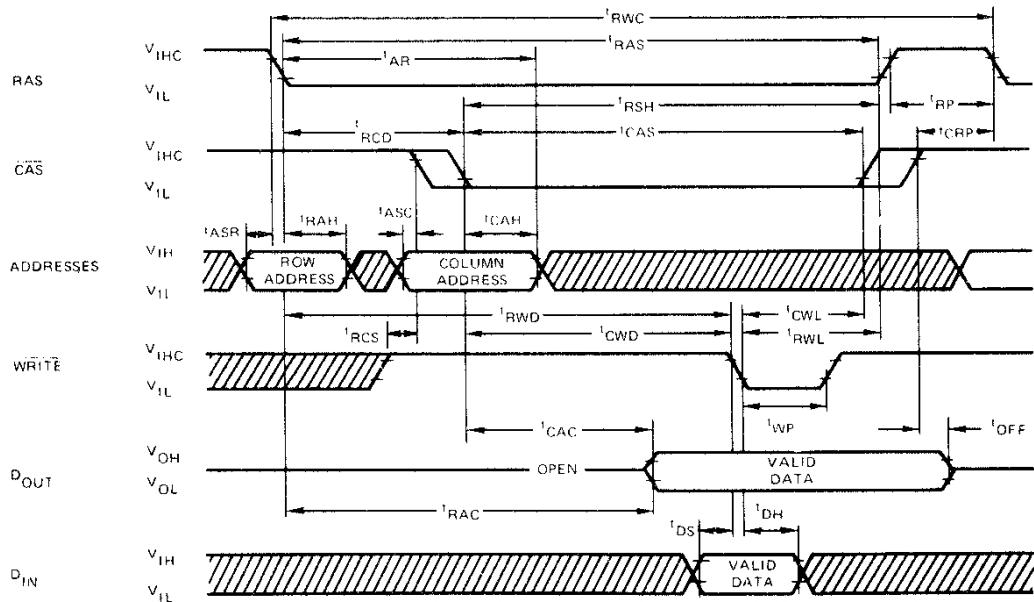
### READ CYCLE



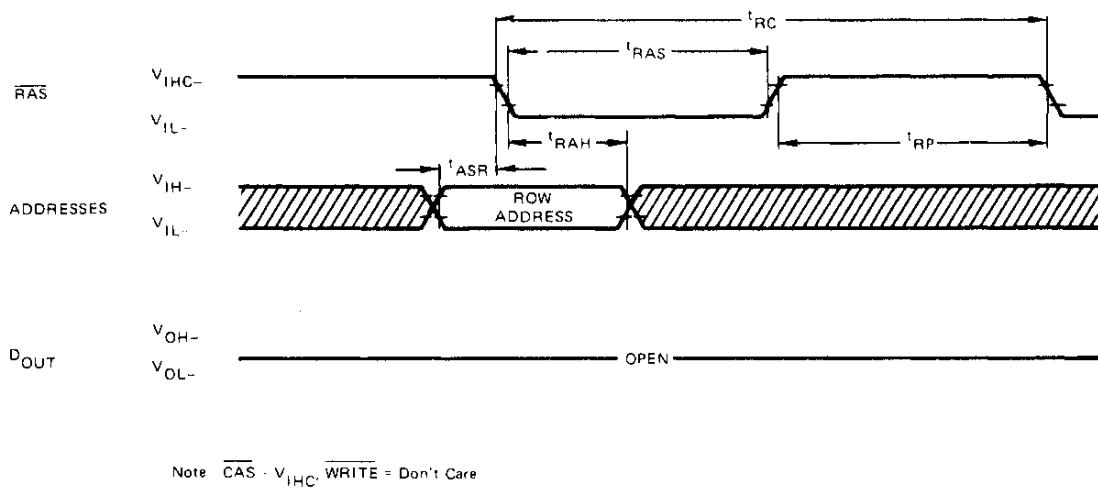
### WRITE CYCLE



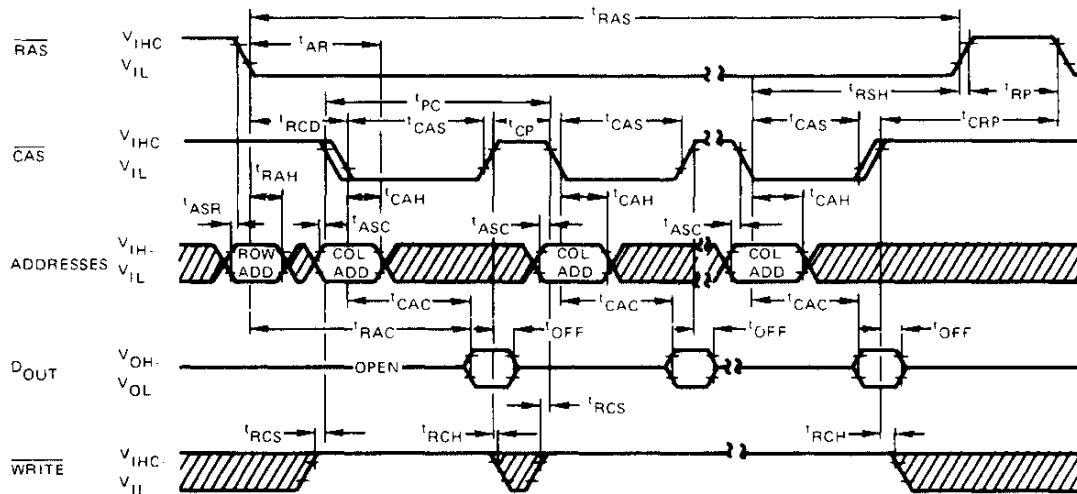
### READ-WRITE/READ-MODIFY-WRITE CYCLE



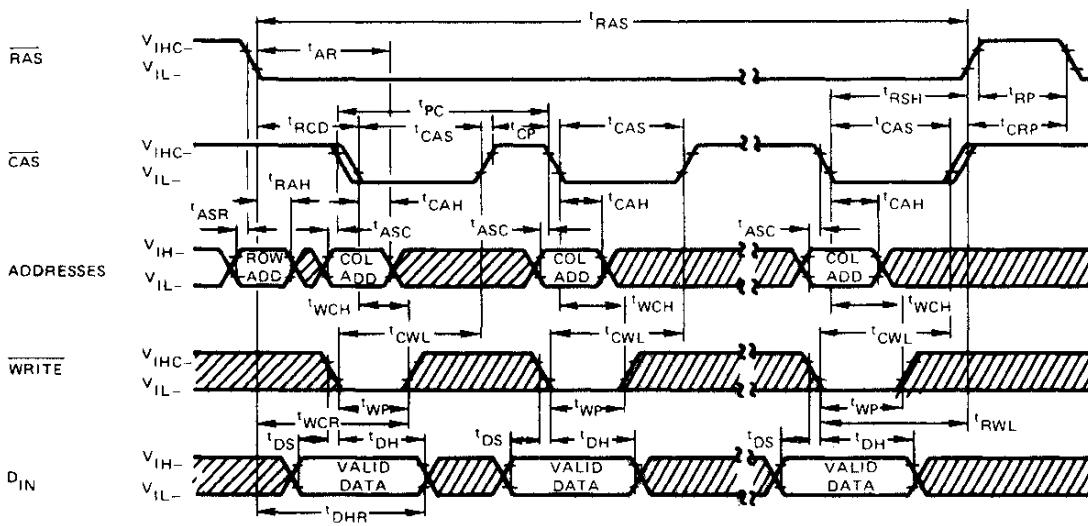
### "RAS-ONLY" REFRESH CYCLE



### PAGE MODE READ CYCLE



### PAGE MODE WRITE CYCLE



The 14 address bits required to decode 1 of 16,384 bit locations are multiplexed onto the 7 address pins and then latched on the chip with the use of the Row Address Strobe (RAS), and the Column Address Strobe (CAS). The 7 bit row address is first applied and RAS is then brought low. After the RAS hold time has elapsed, the 7 bit column address is applied and CAS is brought low. Since the column address is not needed internally until a time of  $t_{CRD\ MAX}$  after the row address, this multiplexing operation imposes no penalty on access time as long as CAS is applied no later than  $t_{CRD\ MAX}$ . If this time is exceeded, access time will be defined from CAS instead of RAS.

For a write operation, the input data is latched on the chip by the negative going edge of WRITE or CAS, whichever occurs later. If WRITE is active before CAS, this is an "early WRITE" cycle and data out will remain in the high impedance state throughout the cycle. For a READ, WRITE, OR READ-MODIFY-WRITE cycle, the data output will contain the data in the selected cell after the access time. Data out will assume the high impedance state anytime that CAS goes high.

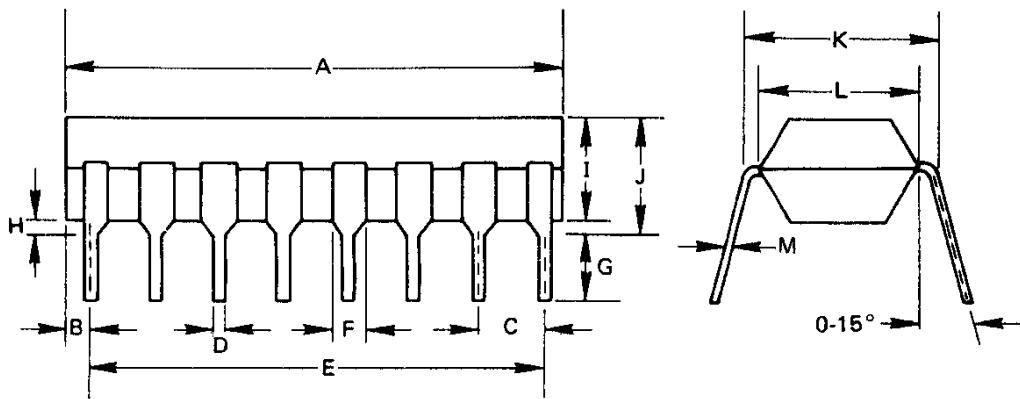
The page mode feature allows the  $\mu$ PD416 to be read or written at multiple column addresses for the same row address. This is accomplished by maintaining a low on RAS and strobing the new column addresses with CAS. This eliminates the setup and hold times for the row address resulting in faster operation.

Refresh of the memory matrix is accomplished by performing a memory cycle at each of the 128 row addresses every 2 milliseconds or less. Because data out is not latched, "RAS only" cycles can be used for simple refreshing operation.

Either RAS and/or CAS can be decoded for chip select function. Unselected chip outputs will remain in the high impedance state.

In order to assure long term reliability,  $V_{BB}$  should be applied first during power up and removed last during power down.

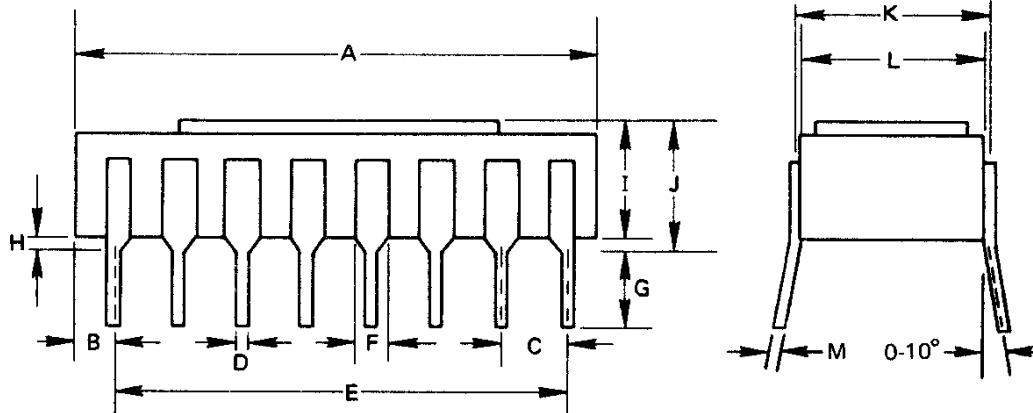
$\mu$ PD416C



(Plastic)

| ITEM | MILLIMETERS                          | INCHES    |
|------|--------------------------------------|-----------|
| A    | 19.4 MAX.                            | 0.76 MAX. |
| B    | 0.81                                 | 0.03      |
| C    | 2.54                                 | 0.10      |
| D    | 0.5                                  | 0.02      |
| E    | 17.78                                | 0.70      |
| F    | 1.3                                  | 0.051     |
| G    | 2.54 MIN.                            | 0.10 MIN. |
| H    | 0.5 MIN.                             | 0.02 MIN. |
| I    | 4.05 MAX.                            | 0.16 MAX. |
| J    | 4.55 MAX.                            | 0.18 MAX. |
| K    | 7.62                                 | 0.30      |
| L    | 6.4                                  | 0.25      |
| M    | <sup>+0.10</sup><br><sub>-0.05</sub> | 0.01      |

$\mu$ PD416D



(Ceramic)

| ITEM | MILLIMETERS | INCHES    |
|------|-------------|-----------|
| A    | 20.5 MAX.   | 0.81 MAX. |
| B    | 1.36        | 0.05      |
| C    | 2.54        | 0.10      |
| D    | 0.5         | 0.02      |
| E    | 17.78       | 0.70      |
| F    | 1.3         | 0.051     |
| G    | 3.5 MIN.    | 0.14 MIN. |
| H    | 0.5 MIN.    | 0.02 MIN. |
| I    | 4.6 MAX.    | 0.18 MAX. |
| J    | 5.1 MAX.    | 0.20 MAX. |
| K    | 7.6         | 0.30      |
| L    | 7.3         | 0.29      |
| M    | 0.27        | 0.01      |